## Signature-based Gröbner Basis Algorithms

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The basic problem

Signature basics

Signature-based criteria

A decade in signature-based Gröbner Basis algorithms

## How to detect zero reductions in advance?

Example
Let $I=\left\langle g_{1}, g_{2}\right\rangle \in \mathbb{Q}[x, y, z], \mathbf{g}_{1}=\mathbf{x y}-z^{2}, \mathbf{g}_{2}=\mathbf{y}^{2}-z^{2}$.
$<$ denotes the reverse lexicographical ordering.

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\operatorname{spol}\left(g_{2}, g_{1}\right) & =x g_{2}-y g_{1}=x y^{2}-x z^{2}-x y^{2}+y z^{2} \\
& =-x z^{2}+y z^{2}
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How to get rid of this zero reduction?

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3. Each $f \in I$ can be represented via some $\alpha \in R^{m}: f=\bar{\alpha}$
4. A signature of $f$ is given by $\mathfrak{s}(f)=\operatorname{lt}_{\prec}(\alpha)$ where $f=\bar{\alpha}$.

Our example again - now with signatures and $\prec_{\text {pot }}$

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g_{2} & =y^{2}-z^{2}, \mathfrak{s}\left(g_{2}\right)=e_{2}, \\
g_{3} & =\operatorname{spol}\left(g_{2}, g_{1}\right)=x g_{2}-y g_{1} \\
\Rightarrow \mathfrak{s}\left(g_{3}\right) & =x \mathfrak{s}\left(g_{2}\right)=x e_{2} .
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Note that $\mathfrak{s}\left(\operatorname{spol}\left(g_{3}, g_{1}\right)\right)=x y e_{2}$ and $\operatorname{Im}\left(g_{1}\right)=x y$.
$\Rightarrow$ We know that $\operatorname{spol}\left(g_{3}, g_{1}\right)$ reduces to zero w.r.t. $G$.

## How do we know this?

General idea: Per signature we only need to compute 1 element for $G$.

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Choose 1 and remove the others.

Our goal: Make good choices.
Our task: Keep signatures correct.

## Think in the module

$\alpha \in R^{m}$ stores all data needed:
$\checkmark$ Polynomial $\bar{\alpha}$ with leading term It $(\bar{\alpha})$.

- Signature $[\mathfrak{s}(\bar{\alpha})=] \mathfrak{s}(\alpha)=\operatorname{lt}(\alpha)$.


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Conventions:
> $\alpha \in R^{m}$ with $\bar{\alpha}=0$ is a syzygy.

- $\mathfrak{s}$-reduction $\widehat{=}$ polynomial reduction while retaining signature
- $\mathfrak{s}$-reductions are always w.r.t. a finite basis $\mathcal{G} \subset R^{m}$.


## Signature-based Gröbner Bases

$\checkmark \mathcal{G}$ is a signature-based Gröbner Basis in signature $T$ if all $\alpha \in R^{m}$ with $\mathfrak{s}(\alpha)=T \mathfrak{s}$-reduce to zero w.r.t. $\mathcal{G}$.

- $\mathcal{G}$ is a signature-based Gröbner Basis if $\mathcal{G}$ is a signature-based Gröbner Basis in all signatures
- If $\mathcal{G}$ is a signature-based Gröbner Basis then $\{\bar{\alpha} \mid \alpha \in \mathcal{G}\}$ is a Gröbner Basis for $\left\langle f_{1}, \ldots, f_{m}\right\rangle$.


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## Remark

In the following we need one detail from signature-based Gröbner Basis computations:

The pair set is ordered by increasing signature.

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## Signature-based criteria



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$$
\mathfrak{s}(\alpha)=\mathfrak{s}(\beta) \quad \Longrightarrow \quad \text { Compute 1, remove } 1 .
$$

Sketch of proof

1. $\mathfrak{s}(\alpha-\beta) \prec \mathfrak{s}(\alpha), \mathfrak{s}(\beta)$.
2. All S-pairs are handled by increasing signature.
$\Rightarrow$ All relatons $\prec \mathfrak{s}(\alpha)$ are known:

$$
\alpha=\beta+\text { elements of smaller signature }
$$

## Signature-based criteria

## S-pairs in signature $T$

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## S-pairs in signature $T$

What are all possible configurations to reach signature $T$ ?

## Signature-based criteria

## S-pairs in signature $T$



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## S-pairs in signature $T$



## Special cases



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1. If a $\alpha$ is a syzygy
$\Longrightarrow$ Go on to next signature.

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$\mathfrak{R}_{T}=\{a \alpha \mid \alpha$ handled by the algorithm and $\mathfrak{s}(a \alpha)=T\}$

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## Revisiting our example with $\prec_{\text {pot }}$

$\mathfrak{s}\left(\operatorname{spol}\left(g_{3}, g_{1}\right)\right)=x y e_{2}$
$\left.\begin{array}{l}g_{1}=x y-z^{2} \\ g_{2}=y^{2}-z^{2}\end{array}\right\} \Rightarrow \operatorname{psyz}\left(g_{2}, g_{1}\right)=g_{1} e_{2}-g_{2} e_{1}=x y e_{2}+\ldots$

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