F5C: A variant of Faugère's F5 algorithm with reduced Gröbner bases

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What is this talk all about?

- Efficient computations of Gröbner bases using Faugère's F5 Algorithm and variants of it
- 2 Explanation of the F5 Algorithm, its criteria used to detect useless pairs, and its points of inefficiency
- OPresentation of the variant F5C which reduces the stated inefficiencies of F5
- **4** Comparison of the variants of F5 under several aspects

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Remark

These **ineffiencies** are the computations of polynomials **redundant** for the Gröbner basis G, i.e. polynomials whose head monomials are multiples of head monomials of other elements already in G.

The following section is about

Introducing Gröbner bases Computation of Gröbner bases Problem of zero reduction

2 The F5 Algorithm

3 Optimizations of F5

4 Comparison of the variants of F5

Main property of Göbner bases

Lemma

Let G be a Gröbner basis of an ideal I. Then for all elements $g_i, g_j \in G$ it holds that

$$\operatorname{Spol}(g_i, g_j) \xrightarrow{G} 0,$$

where

•
$$\operatorname{Spol}(g_i, g_j) = \operatorname{hc}(g_j)u_ig_i - \operatorname{hc}(g_i)u_jg_j$$
 and
• $u_k = \frac{\operatorname{lcm}(\operatorname{hm}(g_i), \operatorname{hm}(g_j))}{\operatorname{hm}(g_k)}$ for $k \in \{i, j\}$.

1
$$G = \emptyset$$

2 $G := G \cup \{f_i\}$ for all $i \in \{1, ..., m\}$

$$\textbf{3 Set } P := \{ \operatorname{Spol}(g_i, g_j) \mid g_i, g_j \in G, i \neq j \}$$

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 - (a) If $p \xrightarrow{G} 0 \Rightarrow$ no new information Go on with the next element in *P*.

The standard **Buchberger Algorithm** to compute *G* follows easily from the previous stated property of *G*: **Input:** Ideal $I = \langle f_1, \ldots, f_m \rangle$ **Output:** Gröbner basis *G* of *I*

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 new information
Add h to G.

Build new S-polynomials with h and add them to P.

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 - (b) If p → h ≠ 0 ⇒ new information Add h to G.
 Build new S-polynomials with h and add them to P.
 Go on with the next element in P.
- **5** When there is no pair left we are done and *G* is a Gröbner basis of *I*.

Example

Assume the ideal $I = \langle g_1, g_2 \rangle \lhd \mathbb{Q}[x, y, z]$ where $g_1 = xy - z^2$, $g_2 = y^2 - z^2$.

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$$Spol(g_2, g_1) = xy^2 - xz^2 - xy^2 + yz^2 = -xz^2 + yz^2,$$

we get a new element $g_3 = xz^2 - yz^2$ for G.

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Now we can reduce further with z^2g_2 :

$$-y^2z^2 + z^4 + y^2z^2 - z^4 = 0.$$

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1 Introducing Gröbner bases

2 The F5 Algorithm F5 basics Computing Gröbner bases incrementally The inefficiency of F5

3 Optimizations of F5

4 Comparison of the variants of F5

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Now we see that $S(\operatorname{Spol}(g_3, g_1)) = (xy, 2)$ and $\operatorname{hm}(g_1) = xy$. \Rightarrow In F5 we **know** that $\operatorname{Spol}(g_3, g_1)$ will reduce to zero!

How does this work?

To understand the criteria of F5 on which this knowledge of zero reduction is based on we first need to give a general overview of a slightly different approach of implementing a Gröbner basis algorithm:

Computing Gröbner bases incrementally

Incremental nature of the F5 Algorithm

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Remark

Note that from this point on $f_i = g_i$ is no longer true for all $i \in \{1, ..., m\}$, due to possible intermediate computations of S-polynomials.

F5 and Rewritten Criterion

Theorem (F5 Criterion)

An S-polynomial $\operatorname{Spol}(g_i, g_j) = u_i g_i - u_j g_j$ does not need to be computed, let alone reduced, if for $k \in \{i, j\}$ and $\mathcal{S}(g_k) = (t_k, \ell_k)$ there exists an element g in G_{ℓ_k-1} such that

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$$\nu > k$$
 and $t_{\nu} \mid u_k t_k$.

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Example

In F5 the following can happen:

1 If xg_i satisfies the F5 Criterion \Rightarrow **no reduction**!

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Complexity of top-reduction in F5

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 - (a) **No reduction** of g_i , but searching for another possible reducer of it.
 - (b) a new **S-polynomial** $g_{\text{new}} := xg_j g_i$ whereas $S(g_{\text{new}}) = (xt_j, \ell)$.

Redundant polynomials

Example

Assume that there is **no other reducer** of g_i .

⇒ In the first two cases g_i is added to G but $hm(g_j) | hm(g_i)$. ⇒ g_i is redundant for G.

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But. . .

For the F5 Algorithm itself and the criteria based on the signatures g_i could be necessary **in this iteration step**!

 \Rightarrow Disrespecting the way F5 top-reduces polynomials would harm the correctness of F5 in this iteration step!

Points of inefficiency

The complexity of top-reduction in F5 leads to an **inefficiency**, namely we have way too many polynomials in the intermediate G_i s

- 1 which are possible reducers,
 - \Rightarrow more checks for divisibility and the criteria have to be done,
- ② with which we compute newly S-polynomials.
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Question

How can these two points be avoided as far as possible?

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- 1 Introducing Gröbner bases
- 2 The F5 Algorithm

3 Optimizations of F5

F5R: F5 Algorithm Reducing by reduced Gröbner bases F5C: F5 Algorithm Computing with reduced Gröbner bases

4 Comparison of the variants of F5

F5R: reduced GB reduction

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- **1** Compute a Gröbner basis G_i of $\langle f_1, \ldots, f_i \rangle$.
- **2** Compute the reduced Gröbner basis B_i of G_i .
- **3** Compute a Gröbner basis G_{i+1} of $\langle f_1, \ldots, f_{i+1} \rangle$ where
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 - (a) G_i is used to build the new pairs with f_{i+1} ,
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 \Rightarrow Fewer reductions in F5R but still the same number of pairs considered and polynomials generated as in F5.

B_i only for reduction?

Question

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Answer

Interreducing G_i to $B_i \leftrightarrow$ reduction steps rejected by F5

 \Rightarrow Reducing G_i to B_i renders the data saved in the **signatures** of the polynomials **useless**!

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 - (a) B_i is used to build new pairs with f_{i+1} ,
 - (b) B_i is used to reduce polynomials.
- \Rightarrow Fewer reductions than F5 & F5R and fewer polynomials generated and considered during the algorithm

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Recomputation of signatures

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Recomputation of signatures

- 1 Delete all signatures.
- **2** Interreduce G_i to B_i .
- **3** For each element $g_k \in B_i$ set $S(g_k) = (1, k)$.
- General elements g_j, g_k ∈ B_i recompute signatures for Spol(g_j, g_k).
- Start the next iteration step with f_{i+1} by computing all pairs with elements from B_i.

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Further improvement

In 2009 Perry & Eder have shown that in F5C it is not necessary to recompute the signatures of $\text{Spol}(g_j, g_k)$ for $g_j, g_k \in B_i$.

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- 1 Delete all signatures.
- **2** Interreduce G_i to B_i .
- 3 For each $g_k \in B_i$ set $\mathcal{S}(g_k) = (1, \mathbf{k})$.
- **4** Start the next iteration step with f_{i+1} .

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 Comparison of the variants of F5 Implementations Comparison of the variants Comparison of F5, F5R & F5C

Implementations

Three free available implementations:

- 1 F5, F5R & F5C as a SINGULAR library (Perry & Eder)
- F5, F5R & F5C implemented in Python for Sage (Perry & Albrecht): F4-ish reduction possible.
- **3** F5, F5R & F5C implementation in the SINGULAR kernel: **under development**

Preliminaries

We are comparing the three variants of F5 in the way that we use the **same implementation** of the **core algorithm** for all variants.

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Moreover we do not only compare

- 1 timings, but also
- 2 the number of reductions, and
- **3** the number of polynomials generated.

Timings

Instead of the timings themselves we present the ratios of the timings comparing the three variants.

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system	F5R / F5	F5C / F5R	F5C / F5
Katsura 7	1.13	0.94	1.06
Katsura 8	1.09	0.75	0.83
Katsura 9	1.14	0.54	0.62
Schrans-Troost	1.01	0.70	0.71
Cyclic 6	0.60	1.00	0.60
Cyclic 7	0.80	0.61	0.49
Cyclic 8	0.93	0.66	0.62

Number of reductions

system	# red in F5	# red in F5R	# red in F5C
Katsura 4	774	289	222
Katsura 5	14,597	5,355	3,985
Katsura 6	9,506,808	77,756	58,082
Cyclic 5	512	506	446
Cyclic 6	41,333	23,780	14,167

Number of polynomials generated

In the following we present internal data from the computation of Katsura 9.

i	$\# G_i$ in F5	$\# G_i$ in F5C	$\max \#P$ in F5	$\max \#P$ in F5C
2	2	2	none	none
3	4	4	1	1
4	8	8	2	2
5	16	15	4	4
6	32	29	8	6
7	60	51	17	12
8	132	109	29	29
9	524	472	89	71
10	1,165	778	276	89

Conclusions

F5C

is way faster, is more efficient, computes fewer data, computes fewer reductions

than F5 and F5R.

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